The Vector™ V123/133 is Hemisphere GNSS’ all-in-one single-frequency, multi-GNSS smart antenna which provides Atlas decimeter-level position and precise heading. This rugged design is sealed for the harshest environments and is a great solution for professional marine and other challenging applications.

The all-in-one V123/133 combines simple installation with consistent and precise heading accuracy and decimeter positioning.

**Key Features**
- Simple all-in-one single-frequency, multi-GNSS heading solution
- Single-frequency GPS/GLONASS/BeiDou/Galileo QZSS
- Atlas® L-band and beacon (V133) capable
- Integrated gyroscope provides smooth, fast heading reacquisition
- Reliable < 1° per minute heading for periods up to 3 minutes when loss of GNSS has occurred
- Fully rugged solution for the harshest environments
## GNSS Receiver Specifications

**Receiver Type:** Vector GNSS Receiver

**Signals Received:** GPS, GLONASS, BeiDou, Galileo, QZSS, and Atlas

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Channels</td>
<td>424</td>
</tr>
<tr>
<td>GPS Sensitivity</td>
<td>-142 dBm</td>
</tr>
<tr>
<td>SBAS Tracking</td>
<td>2-channel, parallel tracking</td>
</tr>
<tr>
<td>Update Rate</td>
<td>20 Hz standard, 50 Hz optional</td>
</tr>
<tr>
<td>Timing (1 PPS)</td>
<td></td>
</tr>
<tr>
<td>Accuracy</td>
<td>20 ns</td>
</tr>
<tr>
<td>Rate of Turn</td>
<td>100°/s maximum</td>
</tr>
<tr>
<td>Compass Safe Distance</td>
<td>50 cm</td>
</tr>
<tr>
<td>Cold Start</td>
<td>60 s (no almanac or RTC)</td>
</tr>
<tr>
<td>Warm Start</td>
<td>30 s typical (almanac and RTC)</td>
</tr>
<tr>
<td>Hot Start</td>
<td>10 s typical (almanac, RTC and position)</td>
</tr>
<tr>
<td>Heading Fix</td>
<td>10 s typical (valid position)</td>
</tr>
<tr>
<td>Antenna Input Impedance</td>
<td>50 Ω</td>
</tr>
<tr>
<td>Maximum Speed</td>
<td>1,850 kph (999 kts)</td>
</tr>
<tr>
<td>Altitude</td>
<td>18,000 m (59,055 ft)</td>
</tr>
<tr>
<td>Differential Options</td>
<td>SBAS, Atlas (L-band)</td>
</tr>
</tbody>
</table>

### Accuracy

**Position:** RMS (67%)

<table>
<thead>
<tr>
<th>Mode</th>
<th>Accuracy (RMS)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Autonomous, no SA</td>
<td>1.2 m</td>
</tr>
<tr>
<td>SBAS</td>
<td>0.3 m</td>
</tr>
<tr>
<td>Atlas (L-Band)</td>
<td>0.3 m</td>
</tr>
</tbody>
</table>

**Heading (RMS):** 0.3°

**Pitch/Roll (RMS):** 1°

**Heave (RMS):** 30 cm (DGPS) to 10 cm (Atlas)

### Beacon Receiver Specifications

**Channels:** 2-channel, parallel tracking

**Frequency Range:** 283.5 to 325 kHz

**Operating Modes:** Manual, Automatic, and Database

**Compliance:** IEC 61108-4 beacon standard

### L-Band Receiver Specifications

**Receiver Type:** Single Channel

**Channels:** 1,525 to 1,560 MHz

**Sensitivity:** -130 dBm

**Channel Spacing:** 5 kHz

**Satellite Selection:** Manual or Automatic

**Reacquisition Time:** 15 sec (typical)

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1. Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionoispheric activity
2. Depends on multipath environment, number of satellites in view, WAAS coverage and satellite geometry
3. Based on a 40-second time constant
4. This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines “vicinity” relative to the compass as within 5 m (16.4 ft) separation
5. Hemisphere GNSS proprietary
6. Requires a Hemisphere GNSS subscription
7. With future firmware upgrade and activation
8. V133 only

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## Communications

**Ports:** 1x RS232, 1x RS422, 1x half-duplex

**Baud Rates:**

- **Correction I/O:**
  - ATLAS: Hemisphere GNSS proprietary, RTCM v3.3 (DGPS)
  - NMEA 0183, NMEA 2000, Hemisphere GNSS binary

**Data I/O Protocol:**

- **Timing Output:**
  - 1 PPS (active high, rising edge sync, 10 kΩ, 10 pF load)

**Event Marker Input:**

- Active low, falling edge sync, 10 kΩ, 10 pF load

**Heading Warning I/O:**

- Open relay system indicates invalid heading

### Power

**Input Voltage:** 9 - 36 VDC with reverse polarity operation

**Power Consumption:** (multi-GNSS, typical continuous draw @ 12V)

<table>
<thead>
<tr>
<th>SBAS</th>
<th>Beacon</th>
<th>Atlas</th>
</tr>
</thead>
<tbody>
<tr>
<td>V123</td>
<td>3.9 W</td>
<td>4.3 W</td>
</tr>
<tr>
<td>V133</td>
<td>-</td>
<td>4.2 W</td>
</tr>
</tbody>
</table>

**Current Consumption:** (multi-GNSS, typical continuous draw @ 12V)

<table>
<thead>
<tr>
<th>SBAS</th>
<th>Beacon</th>
<th>Atlas</th>
</tr>
</thead>
<tbody>
<tr>
<td>V123</td>
<td>0.33 A</td>
<td>0.36 A</td>
</tr>
<tr>
<td>V133</td>
<td>-</td>
<td>0.35 A</td>
</tr>
</tbody>
</table>

**Reverse Polarity Protection:** Yes

### Environmental

**Operating Temperature:**

- -40°C to + 70°C (-40°F to + 158°F)

**Humidity:**

- 95% non-condensing

**Vibration:**

- IEC60945 Section 8.7

**EMC:**

- IEC60945 FCC part 15 Subpart B, CISPR32

**IMO Wheelmark Certification:** MED/4.41 Transmitting Heading Device THD (GNSS Method)

**Enclosure:** IP66/IP69

### Mechanical

**Dimensions:**

- 66.5 L x 20.8 W x 14.6 H (cm)
- 26.2 L x 8.2 W x 5.8 H (in)

**Weight:**

- V123: 2.1 kg (4.6 lb)
- V133: 2.4 kg (5.4 lb)

**Event Marker Input:**

- 1 PPS (active high, rising edge sync, 10 kΩ, 10 pF load)

**Data I/O Protocol:**

- 1x RS232, 1x RS422, 1x half-duplex

**Baud Rates:**

- **Correction I/O:**
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- Active low, falling edge sync, 10 kΩ, 10 pF load

**Heading Warning I/O:**

- Open relay system indicates invalid heading

### Aiding Devices

**Gyro:**

- Integrated gyroscope provides smooth heading, fast heading reacquisition and reliable < 1° per minute heading for periods up to 3 minutes when loss of GNSS has occurred

**Provide pitch, roll and data assist in fast start-up and reacquisition of heading solution

**Tilt Sensors:**

- 18-pin environmentally sealed